

# Integrated GIS and Geostatistical Analysis for Evaluation of Corrosion in Oil Steel Storage Tank

A. Kh. Embaby

Faculty of Engineering, Mining and Petroleum Dept., Al-Azhar University, Cairo, Egypt

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**Abstract** In this investigation, the effect of time on variation of oil tank thickness using the geographic information systems (GIS) and geostatistical analysis. The variograms were created to describe the spatial variability of the tank thickness. The chosen models were used to create a corrosion map through creating many layers using GIS. ArcInfo 9.3 software package was used to achieve this study.

**Keywords** GIS technique, Corrosion, Variograms, Prediction modeling

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## 1. Introduction

Geographic Information Systems (GIS) are important aspects of spatial data infrastructure, and they are also a robust and integrated software system [1-3]. The GIS systematically combines sciences such as graphics, imaging, geology, geography, remote sensing, mapping, artificial intelligence, and computer science. GIS is used in many areas, including geology, oil, oceans, remote sensing, urban and regional planning, surveying, water supply systems, and management of communication facilities, gas, transportation, electric power, agriculture and irrigation, and extinction of fires. Epidemics, land resources, disaster monitoring, regional crops, trade, transport, tourism, ecology, environment and population subsystems. The role of GIS in these applications is to provide users and decision makers with effective tools to solve complex, disorganized or semi-structured spatial problems [4-8].

A steady supply of oil and gas for points of export or processing is required for the oil and gas industry. Lines and line components will suffer from material degradation changes in fluid compositions, pressures and temperatures. This degradation of materials leads to the loss of mechanical properties, such as resistance, ductility, impact resistance, etc. This leads to loss of material, thickness, and sometimes to final destruction [9-12]. Corrosion of pipelines, pressure vessels and storage tanks is a major problem in the petrochemical and nuclear industries. In these industries, pipelines, pressure vessels, and tanks often transport hazardous or valuable liquids. The environmental and economic consequences of any leaks can have serious

consequences. Structures requiring verification are often large and partially accessible [9]. Verification and maintenance strategies for damage detection can be costly, and economic planning is a must [13]. Recent advances in the GIS field will provide new possibilities for engineers to examine corrosion spatial distribution. Mineral thickness mapping is the key procedure for identifying ideas and hypotheses for this problem in different geographical regions.

Additionally, proper visualization of spatial structure and corrosion can help managers to solve the problem and assess the safety factor. geostatistical analysis are used in GIS to evaluate unknown sample properties among known sampling points. The two most commonly used methods are kriging and conditional modeling. Both methods calculate sample property values based on specific weight values of sample values in close locations [13]. Great efforts have been devoted to develop engineering models to predict corrosion degradation in terms of determinism and probability. Sadawy et al. [9] studied the change in thickness of the oil reservoir as a single region using geostatic analysis. An attempt was made to study the change in the thickness of the oil reservoir by dividing the reservoir into three separate regions to study similarities and changes in different regions [13].

## 2. Experimental Work

### 2.1. Material

In the present study, a steel oil storage tank (T-3510A) used for oil to El-hamra terminal, Western desert, Egypt, was used. The tank consists of nineteen plates every plate has nine meters long and 2.4 meters width which was arranged through the tank shell in three courses. The tank having a chemical composition of C 0.21%, Mn 1.5%, S 0.045% and

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\* Corresponding author:

Abdoembaby\_72@yahoo.com (A. Kh. Embaby)

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Fe balance.

## 2.2. Ultrasonic Measurements

The ultrasonic measurements were carried out by Krautkramer DM4 at fixed intervals of 1.2 m  $\times$  4.5 m (Figure 1). The ultrasonic thickness gauge was calibrated before reading by standard calibration block with variable thickness.

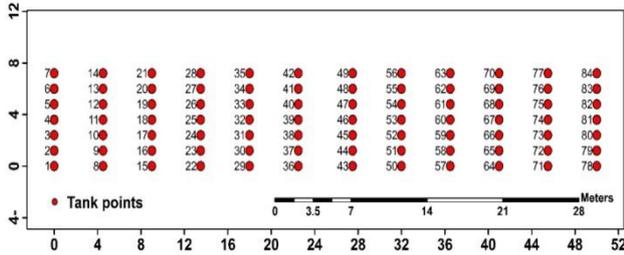


Figure 1. Location map of tank points with point numbers

## 2.3. GIS Database for Corrosion in Steel Storage Tank

The process of finding the locations that represent the different thicknesses of steel storage tank is important process in petroleum industry, which helps in the predication of the corrosion by using the optimum method. The database of corrosion in steel storage tank built in GIS ArcInfo 9.3 software. Whereas these maps are considered as the base map to which all thematic data are spatially linked. In This map, there are 84 tank point locations as shown in Figure. 1. The following steps were performed to achieve our study:

1. The 84 tank point locations data associated with study storage tank is imported to Microsoft Excel 2012 software and exported in dbf (data base file) extension to ArcInfo 9.3 software. Then the point features (point locations) and associated tables are generated and converted to shape file.
2. Creating interpolated TIN (Triangulated Irregular Network) for 84 tank point locations, which are consistent with the prediction of corrosion tank by using 3D Analyst menu.
3. Converting the interpolated TIN for each year at 2004, 2006, 2008 and 2010 to raster. Then convert this raster to grid of points.
4. The shape file of all converted points is created by join the grids of points of corrosion steel storage tank based on spatial location.
5. Using GIS query to find the locations that high and low corrosion tank thickness.

## 3. Results and Discussions

### 3.1. Statistical Analysis

In order to obtain elementary knowledge about the thickness of steel tank and check the type of distribution and homogeneity, statistical analysis was carried out as shown in Table 1. The mean values of the data sets were 13.25, 11.78,

11.74 and 11.29 mm. for years of 2004, 2006, 2008 and 2010, which were close to the median values that were 14.4, 13.0, 13.0 and 12.4 respectively. The coefficient of skewness is relatively high (-1.47, -1.49, -1.512 and -1.513) for data set respectively, indicating that the histograms are approximately a symmetric for all yeas. The very high values of the coefficient of variation reflect the fact that the histograms have a tail of high values. This behavior represents the concentration of corrosive ions or water which allows increasing the electro chemical reaction in selective zone and hence increasing the corrosion rate.

Table 1. Summary statistics of oil storage tank thickness measurements

Statistical factors	Thickness [mm]			
	2004	2006	2008	2010
Minimum	7.4	6.3	5.9	5.2
Maximum	15.2	13.6	13.5	13.1
Range	7.8	7.3	7.6	7.9
Mean	13.25	11.78	11.74	11.29
Median	14.4	13	13	12.4
First quartile	13.95	12.7	12.65	12.2
Third quartile	14.7	13.1	13.1	12.7
95% confidence interval	0.537	0.544	0.546	0.533
99% confidence interval	0.712	0.721	0.724	0.707
Variance	6.135	6.284	6.342	6.044
Standard deviation	2.476	2.506	2.518	2.458
Coefficient of variation	0.186	0.212	0.214	0.217
Skew	-1.478	-1.494	-1.512	-1.513
Kurtosis	0.312	0.302	0.385	0.406

### 3.2. Spatial Dependence Analysis

The semi variogram measures the regionalized spatial variability of  $x(u_a)$ , where  $u_a$  is the coordinate vector at each of the observation points ( $a=1,2,3,\dots,N$ ) for the variable  $x$ . The empirical semi variogram ( $\gamma(h)$ ) is defined as half the average quadratic difference between two observations of a variable separated by a distance vector  $h$  [9,13]:

$$\gamma(h) = \frac{1}{2N(h)} \sum_{a=1}^{N(h)} [x(u_a) - x(u_a + h)]^2 \quad (1)$$

The commonly four theoretical semi variogram models were fitted to the experimental semi-variogram as measured below [9]:

Spherical model:

$$\left\{ \begin{array}{l} \gamma(h) = C_0 + C_1 \left[ \frac{3h}{2a} - \frac{1}{2} \left[ \frac{h}{a} \right]^3 \right] \\ \gamma(h) = C_0 + C_1 \end{array} \right\} \quad \begin{array}{l} \text{for } 0 < h < a \\ \text{for } h > a \end{array} \quad (2)$$

Experimental model:

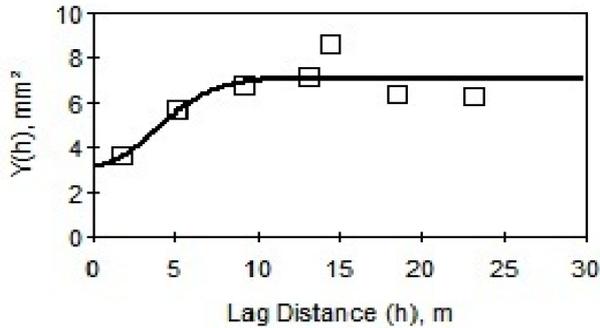
$$\gamma(h) = C_0 + C_1 \left\{ 1 - \exp\left(-\frac{3h}{a}\right) \right\} \quad (3)$$

Gaussian model:

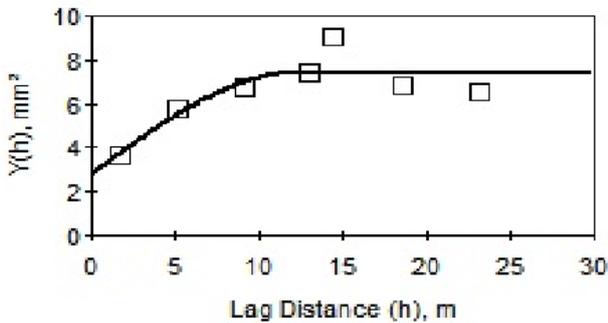
$$\gamma(h) = C_0 + C_1 \left\{ 1 - \exp\left(-\frac{3h^2}{a^2}\right) \right\} \quad (4)$$

**Power model:**

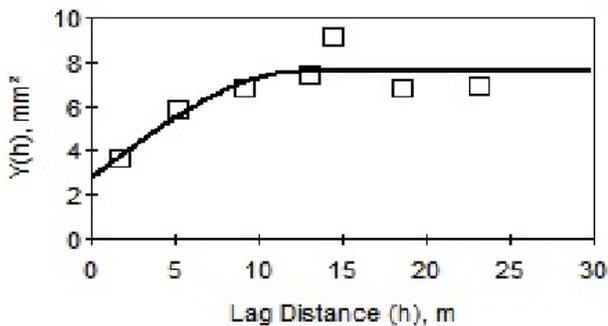
$$\gamma(h) = C_0 + Ah^w \quad 0 < w \leq 2 \quad (5)$$



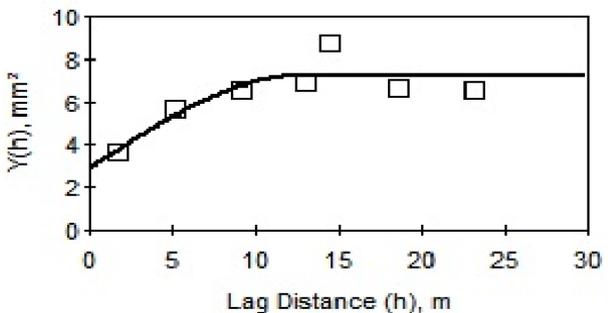
**Figure 2.** Gaussian variogram model for oil steel tank thickness at year 2004



**Figure 3.** Spherical variogram model for oil steel tank thickness at year 2006



**Figure 4.** Spherical variogram model for oil steel tank thickness at year 2008



**Figure 5.** Spherical variogram model for oil steel tank thickness at year 2010

Estimation of the experimental variogram was undertaken for each sample at different time to enable identification of spatial variability in thickness. Different types of semi variogram models used to fit the data Figures (2-5). The Gaussian model had the best fits for year 2004 while Spherical model was the best for other years. Table 2 shows the parameters of the fitted models to the variograms constructed. It can be seen from Table 2 that all variograms have a nugget effect values and high range of influences. This behavior indicates that the variables under study have moderate spatial dependence and high continuity at long scale, but continuity tend to be less at short scale.

**Table 2.** Parameters of spherical and Gaussian variograms models

Zone	Model type	Range(a), m	Sill(C <sub>0</sub> +C), mm <sup>2</sup>	Nugget(C <sub>0</sub> ), mm <sup>2</sup>
2004	Gaussian	8.94	7.09	3.14
2006	Spherical	12.36	7.4	2.8
2008	Spherical	12.5	7.55	2.78
2010	Spherical	12.67	7.2	2.89

#### 4. TIN (Triangulated Irregular Network) Map of Corrosion Tank Map after 6 Year from 2004 to 2010

The obtained semi variogram models were used in GIS to estimate unknown sample properties between known sampling locations. Ordinary Kriging (OK) calculated sample property values based on weighting values assigned to sample values in nearby locations. The OK prediction,

$\hat{Z}_{ok}(x_0)$ , is defined as [9]:

$$\hat{Z}(x_a) = \sum_{n=1}^n \lambda_a^{ok} Z(x_n) \quad (6)$$

With the constraint that the weights,  $\lambda_a^{ok}$  OK, sum to 1 to ensure an unbiased prediction:

$$\sum_{n=1}^n \lambda_a^{ok} = 1 \quad (7)$$

Figures. 6-9 indicates TIN maps of thickness in steel storage tank which was predicted by GIS during the periods of 2004-2010. The locations of high and low thicknesses in steel storage tank and their distribution in the tank body can be determined clearly. As shown in Figs. 6-9 the thicknesses of the tank varied with time from 2004 to 2010, indicating the selective corrosion in the different zones, especially in the zone ranged from 14.333 to 13.467 mm. This behaviour shows the concentration of the corrosive sulphur ions. Hence this can help project engineer to predict the high and low corrosion in steel storage tank as well as helping in decision-making if the tank will be necessary treatment or no.

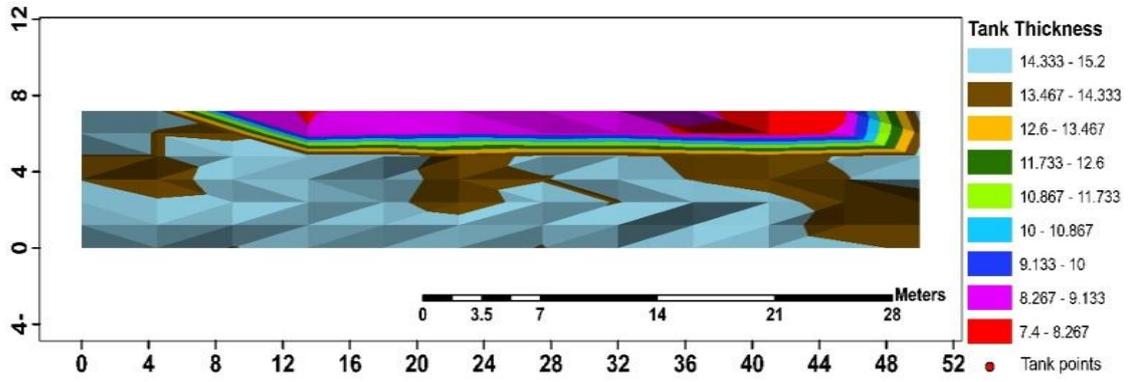


Figure 6. Tank thickness at 2004

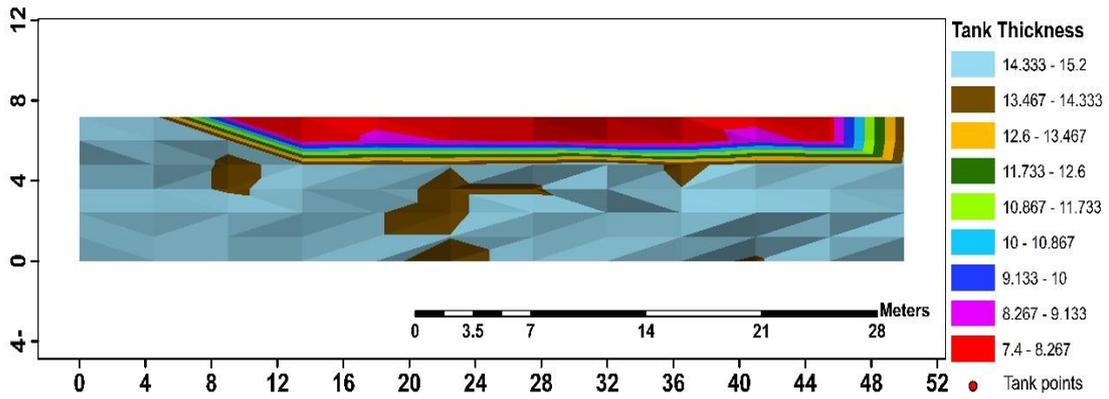


Figure 7. Tank thickness at 2006

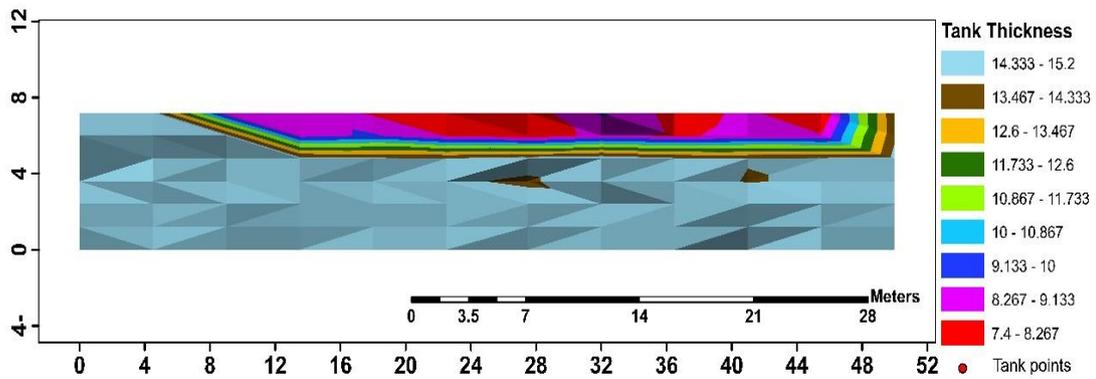


Figure 8. Tank thickness at 2008

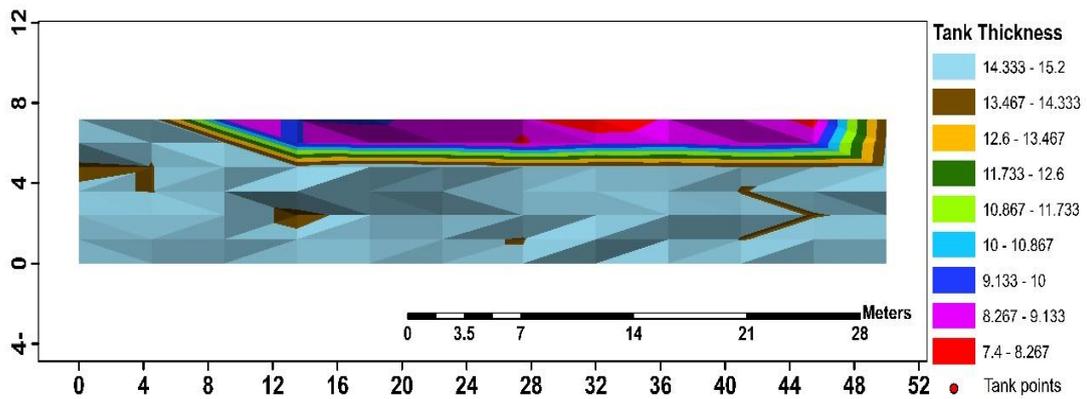


Figure 9. Tank thickness at 2010

## 5. Conclusions

- 1- The integration of GIS-based approaches and geostatistical analysis are valuable when performing spatial studies for predicting corrosion in steel storage tank.
- 2- Modeling the thickness of steel oil tank using geostatistical analysis and GIS indicated that TIN map of tank thickness satisfactorily matched the observed tank thickness values.
- 3- Characterization of spatial dependence by estimating the experimental and theoretical semi variograms indicated that the Gaussian model was generally the best for year 2004 while spherical model described the tank thickness for the other years.

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