

Assessing Overall Structural Integrity of Aluminum 6082-T6 Alloy Dome Structures: Insights from Plasticity Analysis and Members Buckling

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Abstract This study aims to assess the mechanical efficacy of joints constructed from 6082-T6 Aluminum alloy, utilizing both experimental and analytical techniques. The models consider the joint's resistance, stiffness, and deformation capabilities, considering the non-linear behavior caused by the aluminum material characteristics and shape. By employing state-of-the-art Ansys software, this research integrates the response of hexagonal aluminum joints both numerically and experimentally into a complete dome structure. The primary focus is on studying elasto-plastic instability, with particular attention to analyzing the impact of geometric nonlinearities and material behavior. The study explores key parametric quantities that influence dome stability, such as connection type, aluminum joint rotational stiffness, loading form, span length and ratio, ring frequency, members' section area, and early geometric deformation. The overall Structural Integrity was analyzed in relation to member instability, with the propagation of instability being mapped out using the ($P-\delta_{end}$ & $P-\delta_{mid}$) instability graph judgment method. Finally, the present research examines the key parametric quantities that hold influence on steel domes structures and aluminum.

Keywords Instability analysis, Semi-rigid Joints, Semi-rigidly connected dome structures, Buckling analysis, Aluminum Material

1. Introduction

Dome structures have gained widespread use in engineering projects around the world and have seen significant growth in recent years due to the availability of high-strength steel and advanced computer technology. Monolithic domes featuring semirigid joints are particularly noteworthy due to their reduced material usage, attractive appearance, and rapid construction with high accuracy. However, as dome spans increase significantly, instability issues can become critical, making it essential to understand the factors that can influence their stability. The study of instability in the design of monolithic dome structures is thus a relevant issue that requires thorough investigation.

In recent times, researchers showed substantial interest to studying the structural integrity of dome structures [1]. To conduct such studies, researchers have utilized various methods, including continuum shell analogy theories and finite element analysis [2], which have yielded significant insights into the buckling load of dome structures [3]. With the emergence of advanced finite element software and computer technology, however, there is potential for even greater progress in instability research for dome structures. The popularity of nonlinear responses resulting from geometry and material characteristics investigation methods, such as GNA and GMNA, is growing as they replace traditional approaches such as continuum shell analogy and finite element analysis [4,5,6,7,8]. These new methods, coupled with the use of Eigenvalue and nonlinear buckling analyses, provide a deeper insight into the behavior of single-layer domes.

The ultimate load of monolithic domes is heavily influenced by joint inflexibility, which can be determined through both testing and analytical models that provide

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insight into the joint moment-rotation behavior [9]. The analytical models consider various factors, including connection strength, rigidity, and deformation capacity, as well as the nonlinear behavior imposed by the material characteristics and shape. Fathelbab [9] found that joint firmness has a profound effect on load-displacement behavior, highlighting the importance of understanding joint characteristics during the design stage to achieve optimal material usage and structure safety. El-Sheikh [10] study examined the influence of joint flexural rigidity on the global instability and behavior of dome structures, with numerical and test results for ORTZ jointed monolithic domes suggesting that parameters such as geometry, members slenderness, joint inflexibility, and load possibility influence shell behavior [11,12]. Ma et al. [12] also concluded that connection flexural rigidity is a key factor affecting the buckling load of single-layer domes.

In order to comply with Eurocode3 analysis assumptions, the behavior of joints must be taken into account in the exploration of semi-rigidly connected domes. Consequently, the correct projection of partially flexible joint behavior is crucial to the study of these structures. Hexagonal joints with partial bend bearing capacity are often exemplified as typical examples of semi-rigid joints [13]. Furthermore, a monolithic dome with a hexagonal joint should fall under the semi-continuous frame category [13]. Overall, an economical and accurate method for predicting semi-rigid joint behavior is essential for successful analysis and design of semi-rigidly jointed dome structures.

Lately, researchers have been focusing on investigating the buckling behavior of dome structures with semi-rigid connections. Murakami [14] conducted an analytical exploration on the elastic instability of monolithic domes featuring semi-rigid connections under gravity loads. Chenaghlou [15] and Ma et al. [16] investigated the performance of monolithic domes with MERO joints. Kato et al. [17,18] discussed the effect of partially flexible joints on the decrease in failure loads in spherical domes. Numerous studies have investigated the impact of various factors, including member slenderness, geometry, loading pattern, and joint eccentricity on the buckling behavior of dome structures, demonstrating the importance of these variables in analyzing the phenomenon. [19,20,7,8,21,22,23,24]. Chan and Zhou considered beam elements and tangent rigidity while accounting for the early shortage of members [25,26], while Li proposed an approach for the nonlinear analysis of frames [27]. Despite these efforts, further investigation is needed to identify additional key parameters that contribute to the instability of semi-rigidly connected single-layer domes.

To the best of our knowledge, until 2005, the design method for studying the instability of domes assumed that each member was straight, and did not consider the pre-bending of the members. However, during the production, transportation, handling, and assembly of the members, they inevitably become curved in one way or another, which can visibly reduce their ability to sustain load,

provoking structural instability and damaging impacts, especially for compressed slender members. Therefore, there is a need to consider the pre-bending of members in the study of network-like shell structure instability. Subsequently, researchers started focusing on member buckling and complete structure buckling.

In 2006, Su proposed a model for structural component with a middle plastic flexible joint, which assumed that the member was in a completely elastic deformation state before buckling [28]. This joint is thought to appear when the internal force reaches the member's last bearing capacity and can reflect the member's post-buckling compression behavior. Zhou presented a beam element model that considers the early curvature and shear deformation of the members, and studied the failure load of a cable-arc structure using a nonlinear link element that considers the early shortage of the members [29]. In 2007, Sun put forward the Euler geometric nonlinear theory, which established the last bearing capacity of each member and then removed the member that reached the last bearing capacity from GNA [30].

Prior to 2012, there was insufficient research conducted on how buckling of the structural members affects dome structures, and the matter had not been systematically explored due to a lack of engineering application results. Investigating the influence of buckling phenomena exhibited by structural member and complete buckling on dome structures is essential in nonlinear studies and in assessing member buckling assessment methods. The FEM is not satisfactory for describing member buckling, and second-order effects resulting from structure geometric nonlinear influences can result in an increase of members' inner strength, leading to unfavorable states before complete structure buckling. In 2012, Fan et al. developed numerical methods for assessing member buckling in dome structures, which were supported by experimental results [22]. The characteristics of buckling phenomena exhibited by structural member and propagation patterns in dome structures were studied, and the effects of various early shortage features on structure stability were discussed. Additionally, Fan et al. introduced a multi-beam method to simulate members' pre-bending in monolithic dome buckling analyses. Two numerical modeling techniques were employed to investigate the pre-bending and stability of dome members [21].

The current investigation centers on the moment capacity response of aluminum hexagonal joints, which we analyzed using both numerical and experimental techniques. The behavior was incorporated into a full dome structure using advanced Ansys software. The analysis of elastic-plastic instability in aluminum domes included the analysis of nonlinearities in geometry and material behavior effects. Moreover, crucial variables in dome instability, such as connection type, aluminum joint rotational stiffness, loading form, span L and span ratio f/L , ring frequency, members section area, and early geometry shortage, were examined. The study details the propagation of aluminum dome instability and clearly portrays the propagation pattern,

which is compared to the pattern described in a previous study [22]. Finally, this research explores key parameters that influence steel and aluminum dome structures.

2. Geometric Description of the Studied Single Layer Kiewitt Domes

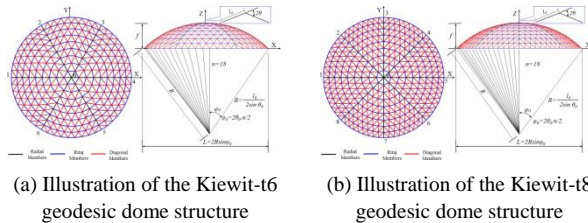


Figure 1. Side-by-side view of K6 and K8 dome geometries in the study

The research models studied in this article are single layer Kiewitt 6 and Kiewitt 8 domes, as depicted in Figure 1.

Table 1. Geometric properties of Kiewitt 6 and Kiewitt 8 domes

Structure type	L (m)	f/L	n	θ_0 (deg.)	φ_0 (deg.)	f (m)	R (m)	l_0 (m)
Kiewitt 6 (K6)	40	1/5	18	2.20	39.51	8.00	29.00	2.22
Kiewitt 6 (K6)	40	1/8	18	1.50	26.96	5.00	42.50	2.22
Kiewitt 6 (K6)	60	1/5	24	1.65	39.51	12.00	43.503	2.50
Kiewitt 6 (K6)	60	1/8	24	1.12	26.96	7.50	63.75	2.50
Kiewitt 8 (K8)	40	1/5	18	2.20	39.51	8.00	29.00	2.22
Kiewitt 8 (K8)	40	1/8	18	1.50	26.96	5.00	42.50	2.22
Kiewitt 8 (K8)	60	1/5	24	1.65	39.51	12.00	43.503	2.50
Kiewitt 8 (K8)	60	1/8	24	1.12	26.96	7.50	63.75	2.50

3. Investigating Dome Instability in Semi-Rigidly Jointed Structures through Numerical Analysis

3.1. Numerical Planar Model with Partially Exible Joints for Investigating the Behavior of a Two-Element Structure

A numerical planar model was created to explore the performance of a dual-member structure with semi-flexible joints, where a digressive vertex force P was imposed on the unit. The model consisted of two connections using combin39 spring units to represent connection rotational stiffness. The model spans $L = 10$ m, with a height of $h = 0.3$ m, and Aluminum tubular members with a diameter of $\Phi 69.85$ 10 were used. When the structure was subjected to the vertex force P , a displacement Δ occurred, causing the early angle between the members, $2\theta_0$, to become 2θ . Equations (3.1) & (3.2) were used to express the correlation between P and θ and between Δ and θ , respectively.

$$P = \frac{2M}{L/2} \cos^2 \theta + 2EA \left(1 - \frac{\cos \theta_0}{\cos \theta} \right) \sin \theta \quad (3.1)$$

$$\Delta = \frac{L}{2} (\tan \theta_0 - \tan \theta) \quad (3.2)$$

Table 1 illustrates the geometry of the analyzed domes, where n represents the number of segments on the radial axis. The domes have fixed vertical boundaries at the base and are supported on a tension ring at the circumference. The span L and the rise/span ratio f/L are specified in Table 1, and the half-subtended angle θ_0 is calculated to represent the inclination of the roof for the members at the dome apex. The members are presumed to be made of Aluminum T6-6082, and the model considers two types of cross-sections: box and tube. Structural characteristics of the examined model are listed in Table 1, including the radius of curvature, spans, and heights of the domes at the center. The members are semi-rigidly jointed at nodes, and their lengths on the rib lines l_0 are also specified in Table 1. The yield strength and Young's modulus of the Aluminum T6-6082 are presumed to be 296 MPa and $E = 69912.23$ MPa, respectively. While the extent of the dome may affect its buckling behaviors, it is not considered significant in this study.

The structure spans 10 meters. The displacement of the member in relation to the horizontal plane is represented by the angular measurement θ , given in radians. The initial value of θ in the horizontal direction is $\theta_0 = 0.060$. The Young's modulus of the material, E_0 , is 69912.23 MPa, and the section area of the member is $A = 4076.3$ mm². The moment produced by the spring, M , can be expressed using equations (3.3):

$$M = K \times 2(\theta_0 - \theta) \quad (3.3)$$

The spring resistance to rotation, K , is used to model the performance of the semi-rigid connections. The resistance to rotation of the tested structural joints is illustrated in Figure 2, for illustration purposes, and its mean value is used as a substitute in the numerical model along with equations (3.1) & (3.2). The average of the rotational response obtained from the aluminum connection test is then substituted into the numerical model of the structure.

By comparing the load-displacement curves presented in Figure 2, the calculated curve exhibits a notable similarity to the experimental curve, which suggests a high degree of similarity between the two. This result indicates that the combin39 spring unit can replicate joint stiffness on structural bearing capacity. Furthermore, the joint inflexibility element model proposed in this study can effectively model the brace plane bearing capacity of a semi-rigid connection structure.

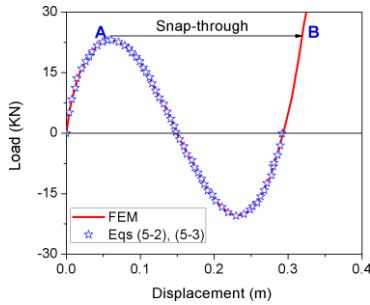


Figure 2. Investigating the behavior of partially exible joints in a two-member structure under external loads

3.2. FE Elements

3.2.1. Features and Capabilities of BEAM189 Element

BEAM189 element is a powerful tool for analyzing beam structures that are thin to moderately robust. It is derived from the Timoshenko [31] beam theory, which accounts for shear strain effects. The 3-D quadratic beam element used in this study permits unconstrained and constrained cross-sectional warping. Each node has six independent parameters, including movements in the three-dimensional coordinate system, as well as rotations about those axes. If needed, there is an alternative seventh independent parameters for warping magnitude. The element is functional for linear, high rotation, and/or large-deformation nonlinear behavior applications. Figure 3 provides an illustration of BEAM189 Element's geometry. However, owing to the restrictions of the 1st-order shear hypothesis, it is only appropriate for evaluating structures of moderate to slender proportions.

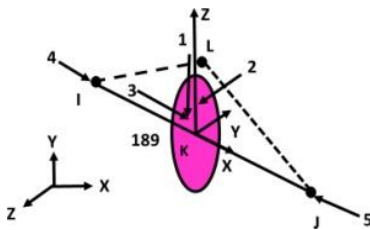


Figure 3. BEAM189 geometric representation

3.2.2. Geometric Properties and Capabilities of COMBIN39 Element

COMBIN39 is an element that exhibits nonlinear force-deflection characteristics. It is applicable in one-dimensional, two-dimensional, or three-dimensional cases for both longitudinal and torsional loads. The longitudinal option has up to three independent parameters at every vertex for movements in the Three-dimensional coordinate system, while the torsional option has three independent parameters for rotations nearly the three spatial dimensions. The element is capable of large displacement and can have two or three independent parameters at every vertex. The structural geometry, vertex locations, and geometric coordinates for this element are illustrated in Figure 4. It is described by two node points and a generalized

force-deflection curve, where the points on the curve represent force or moment versus relative translation or rotation. The loads should be defined on a full 360-degree basis for an asymmetric analysis.

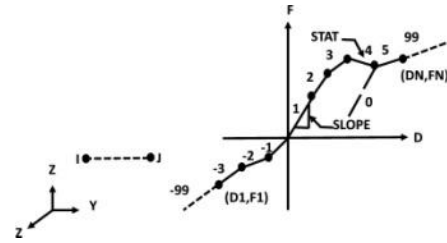


Figure 4. COMBIN39 element geometry and construction illustration

3.2.3. Division and Meshing of Members in Dome Structures Using Beam189 Element

The nodes connecting the members of each structure are presumed to have semi-rigid connections. The base of the structure is fixed and supports a uniformly distributed vertical load. The structures were modeled using ANSYS15.5 Finite-Element software. To model the members, a 3-D linear finite strain beam element using mathematical model of beam theory [31] called Beam189 is utilized. Each member is segmented into eight parts and meshed with four Beam189 elements as displayed in Figure 5. Nonlinearities in geometry and material behavior study (GMNA) is conducted [32] for each dome using Forde and Stierner's proposed method [33]. Figure 6 illustrates the development of plasticity across the cross-section of the Beam189 element.

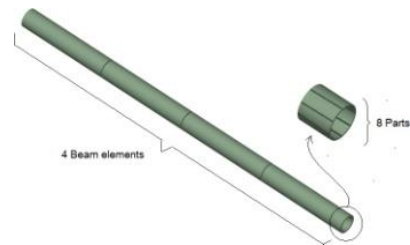


Figure 5. 4 BEAM189 element meshing model for tube members

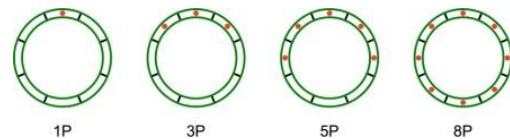


Figure 6. Cross-sectional plasticity development analysis of Beam189 element

3.3. Material Testing and Connection Moment Capacity

3.3.1. Experimental Testing and Mechanical Behavior

The Aluminum 6082-T6 alloy finished product sections shown in Figure 7 were used to create material test samples. These samples were extracted from the Aluminum body in accordance with the Chinese standard for Metal tensile specimen tests [34], and the resulting mechanical properties summarized in Table 2. The resulting mechanical properties

were used to develop an Aluminum material test model that was incorporated into the numerical program used to analyze the domes. The illustration of the model is presented in Figure 9.

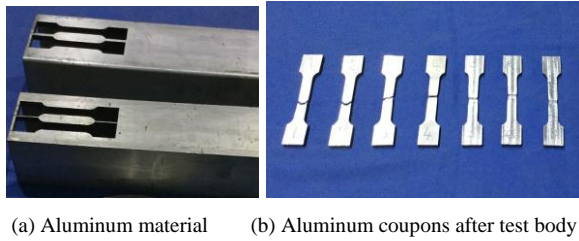


Figure 7. Aluminum material tensile test coupons

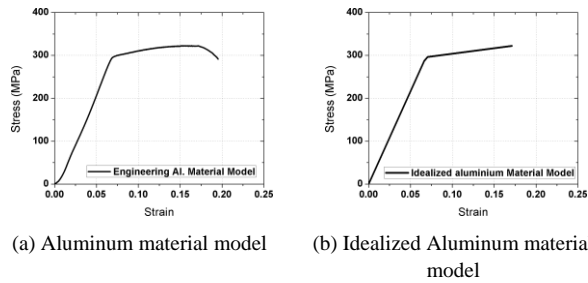


Figure 8. Aluminum 6082-T6 material model for finite element analysis



Figure 9. Testing the strength of Aluminum joints in different orientations under bending loading

3.3.2. Verification of Moment Capacity in Aluminum Hexagonal Joints

Three types of Aluminum Hexagonal joints (T18, T24, and T30) were modeled and experimentally verified in both the bolt direction and orthogonal to the bolt direction [35]. The mechanical capacity of the Aluminum connection model was obtained from experimental tests and integrated into the numerical program. Figure 10 shows the moment capacity

curve for the T30 Aluminum Hexagonal joint for both the experimental and FEM results, which match well in both the bolt direction and orthogonal to the bolt direction. The T30-1 and T30-2 connection models were incorporated into the program as real constant R1 and real constant R2, respectively, in the bolt direction and orthogonal to the bolt direction. The moment capacity was obtained from the mean values of all specimens and displayed in Figure 11.

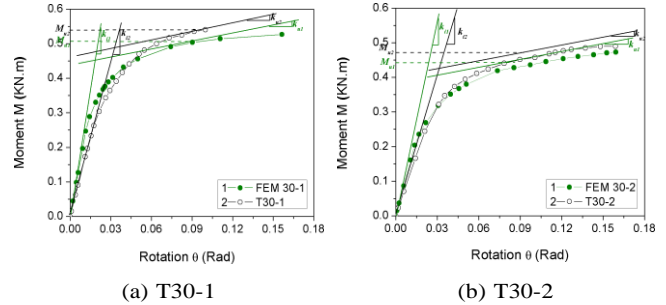


Figure 10. Validating FEM Results with Test Results for T30 Aluminum Hexagonal Joint

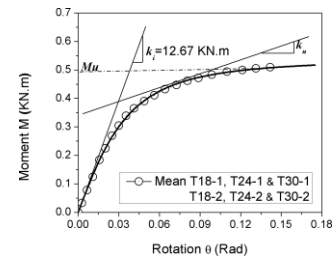


Figure 11. Aluminum Hexagonal joint moment capacity curve

3.4. Investigating the Instability of Domes: A Parametric Analysis Plan

The parametric analysis of the domes' instability was conducted following the plan outlined below:

1. Connection Type: The study considered three connection types: pinned, semi-rigid, and rigid connections.
2. Aluminum Joint Stiffness: Three choices of parametric studies were made based on the domes' aluminum joint moment-rotation curve.
3. Loading Form: Two load types were considered - full uniform permanent load and half variable load uniformly spread across. The variable and permanent load ratio were $p/g = 0, 1/4 \text{ \& } 1/2$.

Table 2. Summary of Aluminum 6082-T6 alloy material coupon test results

Coupon (No)	Thickness (mm)	E_0 (Mpa)	$f_{0,1}$ (Mpa)	$f_{0,2}$ (Mpa)	f_u (Mpa)	$n = \ln 2 / \ln(f_{0,2}/f_{0,1})$	$e = f_{0,2}/E_0$
1	10.00	69912.23	290.38	296	315.31	36.16	0.0042
2	10.00	69912.23	290.38	296	315.31	36.16	0.0042
3	10.00	69912.23	290.38	296	315.31	36.16	0.0042
4	10.00	69912.23	290.38	296	315.31	36.16	0.0042
5	10.00	69912.23	290.38	296	315.31	36.16	0.0042
6	10.00	69912.23	290.38	296	315.31	36.16	0.0042
7	10.00	69912.23	290.38	296	315.31	36.16	0.0042

4. Span L and Span Ratio f/L : The analysis considered two span choices and six span ratios for K6 dome and five span ratios for K8 dome:
 - Span L (m): 40, 60 for K6 dome; & 40 for K8 dome.
 - Span ratio f/L : 1/2; 1/3; 1/4; 1/5; 1/6; 1/8 for K6 dome; & 1/3; 1/4; 1/5; 1/6; 1/8 for K8 dome.
5. Ring Frequency and Members Cross-sectional Area: The study considered four kinds of ring frequencies for each span 6, 7, 8 & 9 for 40m span and 60m span. Members were modeled with tube and box cross-sectional areas (See Table 3).
6. Initial Geometric Imperfections (r): The effects of early geometry defects on final load were studied on the 40m span with a dome span ratio of 1/3; 1/4; 1/5; 1/6; and 1/8. The study considered $L/3000$, $L/2000$, $L/1500$ and $L/1000$ of early geometry defect.

3.4.1. Connection Bending Stiffness Influence

This section of the research article presents the impact of the rotational stiffness of connections on the structural integrity of monolithic domes. To examine this, a more comprehensive parametric analysis was carried out. The study examined the final bearing capacity of K6 and K8 domes with T18, T24, and T30 aluminum connections, considering different joint bending strength. The analysis

involved the following features: a span of 40m or 60m, a span ratio (f/L) of 1/2, 1/3, 1/4, 1/5, 1/6 or 1/8, members with one cross-section group per case, uniform dead load distribution, and three-hinged support conditions. The connection field was set to 150mm and the connection torsional stiffness was assumed to be 0.001 times smaller than the aluminum connections' torsional stiffness. The span limit for the single layer K6 and K8 domes was 40m & 60m, respectively. The critical load versus bending stiffness curves for the joints are presented in Figure 12 & 13. The study found the ultimate load coefficient variation with different joint bending stiffness, which is summarized in Table 4.

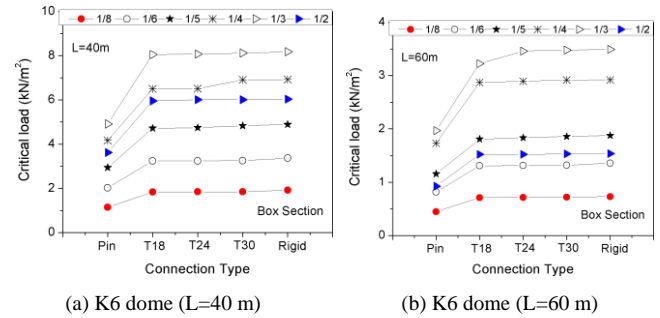


Figure 12. Impact of joint bending stiffness on K6 dome structural performance (Box section members)

Table 3. Frequency Division Numbers for K6 and K8 Domes

K6: Tubular & Box Section Members											
Span	40 m						60 m				
Span Ratio	1/8	1/6	1/5	1/4	1/3	1/2	1/8	1/6	1/5	1/4	1/3
Frequency	09	09	09	09	09	09	12	12	12	12	12
K8: Tubular Section Members						K8: Box Section Members					
Span	40 m						40 m				
Span Ratio	1/8	1/6	1/5	1/4	1/3	---	1/8	1/6	1/5	1/4	1/3
Frequency	09	09	09	09	09	---	09	09	09	09	---

Table 4. Ultimate load coefficient variation in K6 & K8 domes with different joint bending stiffness

K6 Tubular Section											
L	40 m						60 m				
f/L	1/8	1/6	1/5	1/4	1/3	1/2	1/8	1/6	1/5	1/4	1/3
T18	0.952	0.947	0.964	0.963	0.984	0.990	0.991	0.963	0.969	0.912	0.985
T24	0.954	0.951	0.968	0.993	0.991	0.996	0.992	0.964	0.971	0.914	0.988
T30	0.956	0.961	0.969	0.995	0.997	0.997	0.999	0.965	0.973	0.914	0.989
Rigid	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
K6 Box Section											
L	40 m						60 m				
T18	0.956	0.964	0.965	0.938	0.984	0.987	0.975	0.963	0.964	0.983	0.924
T24	0.959	0.964	0.970	0.939	0.987	0.995	0.981	0.967	0.977	0.991	0.991
T30	0.960	0.968	0.989	0.997	0.993	0.996	0.986	0.971	0.990	0.999	0.997
Rigid	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
K8: Tubular Section						K8: Box Section					
L	40 m						40 m				
T18	0.958	0.962	0.969	0.991	0.994	---	0.978	0.934	0.989	0.980	0.988
T24	0.961	0.966	0.971	0.993	0.995	---	0.980	0.939	0.992	0.982	0.992
T30	0.969	0.971	0.977	0.997	0.997	---	0.984	0.944	0.994	0.984	0.993
Rigid	1.00	1.00	1.00	1.00	1.00	---	1.00	1.00	1.00	1.00	1.00

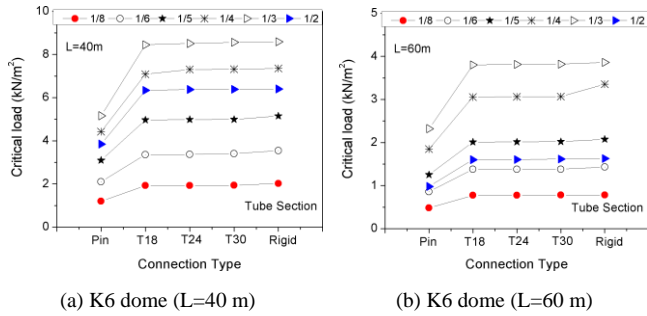


Figure 13. Impact of joint bending stiffness on K6 dome structural performance (Tube section members)

This section of the research article presents the impact of connection rigidity on the structural integrity of monolithic domes. A comprehensive exploration was undertaken to study the final bearing capacity of K6 and K8 domes with T18, T24, and T30 aluminum connections, considering different span lengths, span ratios, and members' cross-sections. The domes' ultimate load coefficient variation with different joint bending stiffness is displayed in Table 4.

It was observed that the unfavorable load limit of the structure increases as the connection rigidity increases with the same span and span ratio. The results of joint strength on the dome's ultimate load is significant and is influenced by the dome's span and rise/span ratio. After the analysis, the final load values for various spans and rise-span ratios of K6 and K8 domes are presented. According to the experimental results, for each type of joint, the ultimate load of a dome with rigid connections is higher than that of a dome with bending connections, according to the data in Table 4. The tables also present the single-layer aluminum dome joint T18, T24, and T30 final bearing capacity ratio and the single-layer dome bearing capacity ratio with rigid joints.

3.4.2. Investigating the Impact of Geometric Deformations on the Final Load of K6 Domes

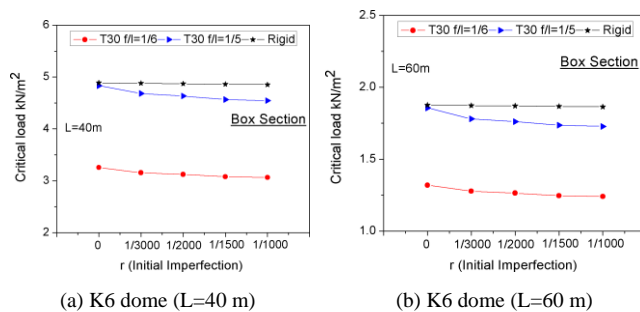


Figure 14. Impact of Initial Geometric irregularities on Critical Load in K6 Domes with Box Sections

In this section, we analyze the effect of early geometric deformations on the final load of K6 domes with T30 aluminum connections and spans of 40m and 60m. We consider four geometric flaw values: $r = L/3000$, $L/2000$, $L/1500$ and $L/1000$, and two span ratios: $(f/L) = 1/5$ and $1/6$. The eigenvalue buckling modal method is applied to evaluate the dome's final load trend. Figure 14 & 15 show

the final load variation for K6 domes with T30 aluminum connections and rigid connections with different geometric flaw values. The study reveals that the final strength value of aluminum bolted joints domes is more sensitive to flaws, while the final strength value of aluminum domes with rigid connections is less sensitive to flaws.

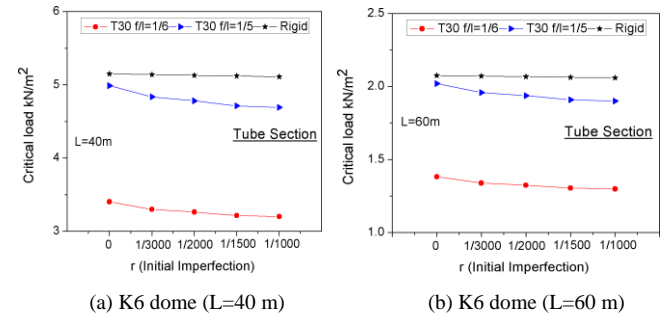


Figure 15. Impact of Initial Geometric irregularities on Critical Load in K6 Domes with Tube Sections

3.4.3. Load Distribution Patterns and Their Effects on the Structural Integrity of Domes

This section explores the effects of different load distributions on the structural integrity of dome structure. Three load distribution patterns are examined: permanent load (uniformly distributed over the full span), variable load (uniformly distributed over half the span), and ratios of $p/g = 0$, $1/4$ & $1/2$. Figure 16 shows the distribution of variable and permanent loads.

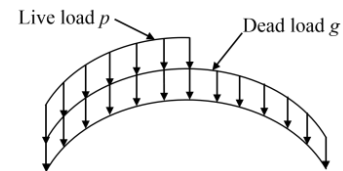


Figure 16. Variable and permanent loads distribution patterns

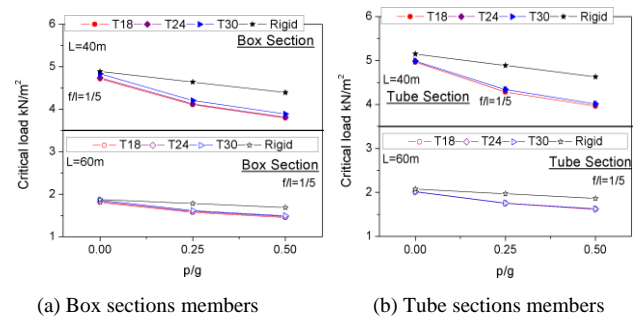


Figure 17. Impact of Load Distribution patterns on Critical Load of Domes

The subsequent variables were selected for the analysis: 40m and 60m spans; span ratio (f/L) of $1/5$; and K6 and K8 dome types. The members in this study have either box or tubular sections.

Figure 17 shows the influence of load distribution on the load capacity of Aluminum K6 dome. An increase in the load distribution ratio results in a reduction of the critical load of the structure.

3.4.4. Effect of Ring Frequency on Critical Load of Dome Structures

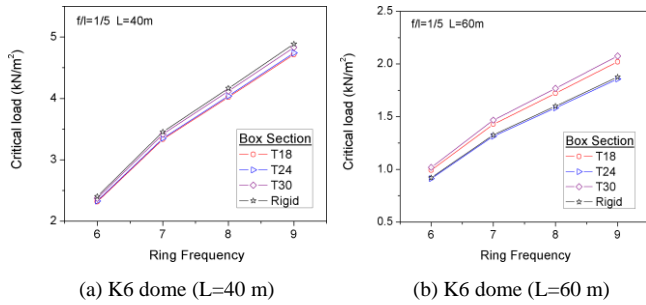


Figure 18. Analysis of ring frequency on the load capacity of aluminum domes (Box section members)

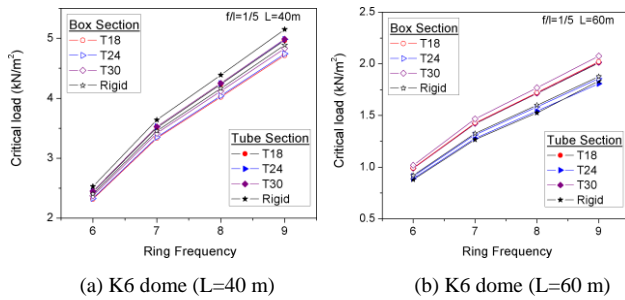


Figure 19. Analysis of ring frequency on the load capacity of aluminum domes (Tube section members)

In this section, the analysis considered four different ring

frequencies for each span (6, 7, 8 & 9 for 40m span and 60m span). The investigation findings are displayed in Figure 18 & 19, and it is evident that as the number of rings increases, the critical load also increases. This can be explained by the rise in dome proper load resulting from an augmentation in the number of members. Similarly, with the same parametric conditions, an augmentation in the span feature results in a decrease in the load capacity. Moreover, the connection stiffness also affects the load capacity.

3.4.5. Span and Height-to-Span Ratio's Effect on Final Load of Aluminum Domes

The study analyzed two spans, $L = 40$ m & $L = 60$ m, with six different span ratios $f/L = 1/2, 1/3, 1/4, 1/5, 1/6$ & $1/8$, using T30 Aluminum connection and K6 and K8 domes to examine the final load variation. The outcome of the semi-rigid dome analysis are presented in Figure 20. It was noted that the final load of the dome intensifies as the span decreases, and it increases from $1/8$ to $1/3$ rise/span ratio, then it decreases at $1/2$ rise/span ratio. Final bearing capacity of semi-rigid Aluminum domes with box and tube members followed the span ratio variation similarly. The effect of members' crosssection on the final load was slightly noticeable in all studied parameters. The final load with box sections was about 4% lower. Table 5 summarizes the final load of K6 and K8 according to different joint bending stiffness, span, and rise/span ratio.

Table 5. Comparing Ultimate Load of K6 & K8 Domes with Different Joint Bending Stiffness, span and rise/span ratio

Connections		K6 dome Ultimate load: Tubular section (KN/m^2)											
L	f/L	40 m						60 m					
		1/8	1/6	1/5	1/4	1/3	1/2	1/8	1/6	1/5	1/4	1/3	1/2
	T18	1.926	3.356	4.966	7.088	8.452	6.339	0.774	1.378	2.010	3.058	3.802	1.602
	T24	1.930	3.367	4.986	7.306	8.514	6.379	0.775	1.379	2.014	3.064	3.814	1.604
	T30	1.933	3.403	4.988	7.319	8.563	6.386	0.780	1.381	2.020	3.065	3.820	1.616
	Rigid	2.023	3.542	5.149	7.358	8.591	6.404	0.781	1.431	2.075	3.354	3.861	1.627
	Max	2.023	3.542	5.149	7.358	8.591	6.404	0.781	1.431	2.075	3.354	3.861	1.627
	Min	1.926	3.356	4.966	7.088	8.452	6.339	0.774	1.378	2.010	3.058	3.802	1.602
	Mean	1.953	3.417	5.022	7.268	8.530	6.377	0.778	1.392	2.030	3.135	3.824	1.612
	Std. dev.	0.040	0.074	0.074	0.106	0.053	0.024	0.003	0.022	0.026	0.126	0.022	0.010
	Coef var.	0.021	0.022	0.015	0.015	0.006	0.004	0.004	0.016	0.013	0.040	0.006	0.006
		K6 dome Ultimate load: Box section (KN/m^2)											
	T18	1.834	3.243	4.718	6.495	8.050	5.957	0.712	1.308	1.809	2.871	3.225	1.523
	T24	1.840	3.244	4.741	6.505	8.073	6.010	0.716	1.313	1.833	2.894	3.461	1.524
	T30	1.841	3.256	4.833	6.904	8.121	6.014	0.720	1.319	1.857	2.917	3.480	1.531
	Rigid	1.918	3.364	4.888	6.924	8.177	6.038	0.730	1.358	1.876	2.920	3.492	1.538
	Max	1.918	3.364	4.888	6.924	8.177	6.038	0.730	1.358	1.876	2.920	3.492	1.538
	Min	1.834	3.243	4.718	6.495	8.050	5.957	0.712	1.308	1.809	2.871	3.225	1.523
	Mean	1.858	3.277	4.795	6.707	8.105	6.005	0.720	1.325	1.844	2.901	3.415	1.529
	Std. dev.	0.035	0.051	0.069	0.207	0.049	0.030	0.007	0.020	0.025	0.020	0.110	0.006
	Coef var.	0.019	0.015	0.014	0.031	0.006	0.005	0.009	0.015	0.014	0.007	0.032	0.004
		K8 dome ultimate load (KN/m^2)											
		Tubular section						Box section					
L		40 m						40 m					
	T18	2.075	3.685	5.404	8.783	10.583	—	2.001	3.387	5.216	8.318	10.054	—
	T24	2.080	3.701	5.414	8.803	10.593	—	2.007	3.405	5.235	8.336	10.095	—
	T30	2.098	3.721	5.444	8.833	10.613	—	2.015	3.425	5.246	8.355	10.107	—
	Rigid	2.165	3.832	5.575	8.861	10.647	—	2.047	3.627	5.276	8.491	10.177	—
	Max	2.165	3.832	5.575	8.861	10.647	—	2.047	3.627	5.276	8.491	10.177	—
	Min	2.075	3.685	5.404	8.783	10.583	—	2.001	3.387	5.216	8.318	10.054	—
	Mean	2.105	3.735	5.459	8.820	10.609	—	2.018	3.461	5.243	8.375	10.108	—
	Std. dev.	0.036	0.058	0.068	0.030	0.024	—	0.018	0.097	0.022	0.068	0.044	—
	Coef var.	0.017	0.015	0.013	0.003	0.002	—	0.009	0.028	0.004	0.008	0.004	—

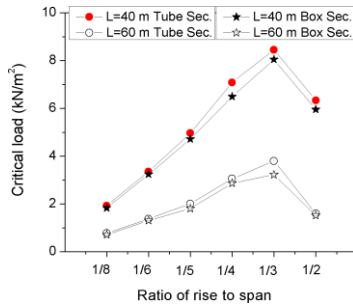


Figure 20. Exploring the Influence of Rise/Span Ratio on Load capacity in Aluminum domes

4. Investigating the Instability of Aluminum Domes: Insights from Plasticity Analysis and Members Buckling

In this section, the instability of aluminum domes is investigated by estimating the areas of structural weakness and analyzing the buckling and the development of plastic deformation of the members. To demonstrate the instability of K6 and K8 domes, three sets were selected and analyzed (as shown in Table 6). For monolithic K6 dome, the sets include $L = 40\text{m}$, $f/L = 1/8$ and $1/5$, and $L = 60\text{m}$, $f/L = 1/8$ and $1/5$. For monolithic K8 dome, the sets include $L = 40\text{m}$, $f/L = 1/8$ and $1/5$. The analysis of the development of plastic deformation indicates the internal stress distribution in the structure.

4.1. Tracing Aluminum Dome Instability: Estimation and Analysis of Weakness Areas

4.1.1. Set 1-A: K6 $L = 40\text{ m}$, $f/L = 1/5$

In this section, the paper discusses the estimation of structure weakening areas and the study of elastic instability of members and plasticity development to trace aluminum dome instability. Three sets of K6 and K8 domes were selected to show their instability, as listed in Table 6. For Dome Set 1-A, instability was found in members between the 5th and 8th ring from the peak. To evaluate the plasticity development of the structure, the GMNA technique was employed, which considers both geometric and material nonlinearity in structural analysis. Eight plasticity increment sizes named on members' cross-section were used to study the development of plasticity under buckling load, as displayed in Figure 21. Plasticity development was observed to start at connections from the 5th circle from the peak.

The analysis categorized the members into three types: stable undistorted members in blue, unstable buckled members in red, and unstable bent members in different colors indicating their level of instability. The instability degree increases from stable undistorted members to unstable buckled members. Unstable bent members are represented in green in the figures that assess member instability, as seen in Figure 22 & 24.

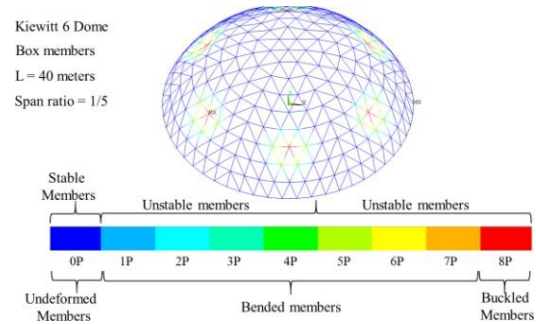


Figure 21. Analyzing Plasticity Development in K6 Domes: Set 1-A

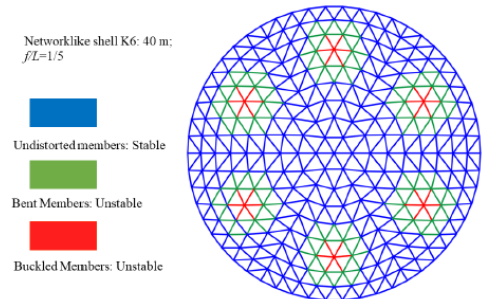


Figure 22. Assessing Member Instability in K6 Dome Set 1-A

4.1.2. Set 1-B: K6 $L = 40\text{ m}$, $f/L = 1/8$

In Dome set 1-B, instability started in members between the secondary and tertiary circle from the peak and progressed to the last members between the eighth and ninth circle. The GMNA approach was employed to examine the plastic deformation development of the structure, whereby eight distinct plasticity increment sizes were identified on the sections of elements, as displayed in Figure 23. The development of plastic deformations begins from members after the 2nd circle from the peak and increases as instability and members' deflection step up with more unstable members. Since set 1-B has a lower rise/span ratio than set 1-A, members' plasticity development level is amplified than that of set 1-A (Figure 24). Members instability assessment is presented in Figure 24, showing that various structure members on the radial axis are more prone to buckling. Members bending second-order effect and bending moment with K6 dome set 1-B intensify.

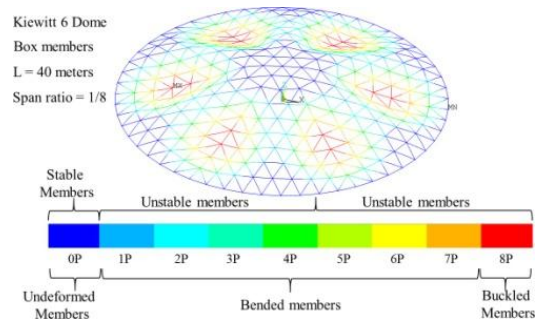


Figure 23. Analyzing Plasticity Development in K6 Domes: Set 1-B

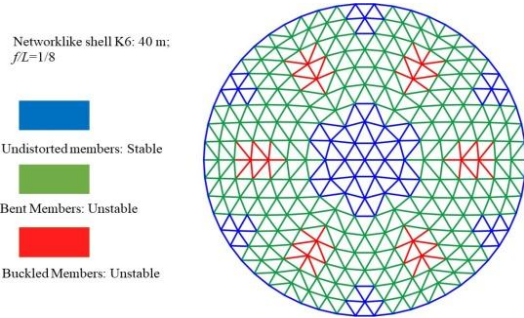
The same analysis process was applied to all selected sets, with the features of set 1-A and set 1-B being explained earlier. The results of all sets are displayed in Table 7.

Table 6. Analysis of instability: Study sets of Kiewitt domes

Study sets	Structure type	L (m)	f/L	n	θ_0 (deg.)	φ_0 (deg.)	f (m)	R (m)	l_0 (m)
Set 1	Set 1-A: Kiewitt 6 (K6)	40	1/5	18	2.20	39.51	8.00	29.00	2.22
	Set 1-B: Kiewitt 6 (K6)	40	1/8	18	1.50	26.96	5.00	42.50	2.22
Set 2	Set 2-A: Kiewitt 8 (K8)	40	1/5	18	2.20	39.51	8.00	29.00	2.22
	Set 2-B: Kiewitt 8 (K8)	40	1/8	18	1.50	26.96	5.00	42.50	2.22
Set 3	Set 3-A: Kiewitt 6 (K6)	60	1/5	24	1.65	39.51	12.00	43.503	2.50
	Set 3-B: Kiewitt 6 (K6)	60	1/8	24	1.12	26.96	7.50	63.75	2.50

Table 7. Aluminum dome instability assessment: Set-wise comparison

Designation	Set1		Set 2		Set 3	
Structure type	K6		K8		K6	
Span	40m		40m		60m	
Total Members	756		1008		1332	
f/L	1/8	1/5	1/8	1/5	1/8	1/5
Joint bending stiffness effect on critical load	↑	↑	↑	↑	↑	↑
Early geometric imperfection effect on critical load	↓	↓	↓	↓	↓	↓
Load distribution effect on critical load	↓	↓	↓	↓	↓	↓
Ring frequency effect on critical load	↑	↑	↑	↑	↑	↑
Rise/span ratio effect on critical load	↑	↑	↑	↑	↑	↑
Instability opening (from summit)	5 th ○	2 nd & 3 rd ○	4 th & 5 th ○	2 nd & 3 rd ○	8 th & 9 th ○	3 th ○
Instability development zone magnitude	7 th & 8 th ○	8 th & 9 th ○	8 th & 9 th ○	8 th & 9 th ○	11 th & 12 th ○	11 th & 12 th ○
Plasticity development opening	5 th ○	2 nd & 3 rd ○	4 th & 5 th ○	2 nd & 3 rd ○	8 th & 9 th ○	4 th ○
Plasticity development zone magnitude	7 th & 8 th ○	8 th & 9 th ○	8 th & 9 th ○	8 th & 9 th ○	11 th & 12 th ○	11 th & 12 th ○
Plasticity increment magnitude	Eight	Eight	Eight	Eight	Eight	Eight
Stable members (%)	20	74	35	40	38	77
Unstable members (%)	80	60	65	60	62	23
Buckled members (%)	9	5	9	9	11	3
Bent members (%)	72	21	56	52	50	20
Buckled Members Paths	→		→		→	

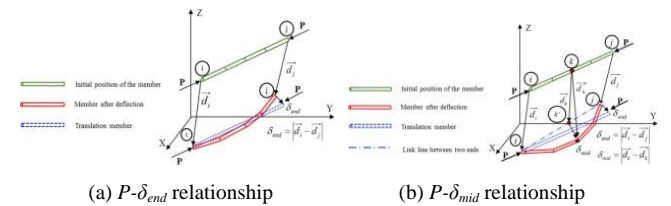
**Figure 24.** Assessing Member Instability in K6 Dome Set 1-B

4.2. Evaluating Dome Structure Instability Using P - δ Relationship Method

Evaluating the instability of a dome structure is a challenging task that requires a rigorous approach. In this study, the P - δ_{end} & P - δ_{mid} relationship method is utilized, as described in previous research [21,22,23,24]. To analyze the instability of the dome, three buckling modes are defined. The stress conditions for members in the dome structure are complex, involving axial compression forces and biaxial bending moments. Since axial compression is the primary cause of member buckling, two types of axial compression member force-position graphs are assumed in the P - δ_{end} & P - δ_{mid} graphs, as displayed in Figure 25 (a) & (b).

The technique of P - δ_{end} & P - δ_{mid} relationship is utilized to examine dome structure in- stability, which is a challenging task. To perform this analysis, three buckling modes are

defined. Since the member stress conditions in dome structures are complicated and involve axial compression forces and biaxial bending moments, two types of axial compression member force-position graphs are assumed in the P - δ_{end} & P - δ_{mid} graphs (Figure 25 (a) and (b)). In Figure 25 (a), P - δ_{end} represents the axial compression load P graph and the relative translation position between two member extremities (δ_{end}). The value of δ_{end} changes with the axial compression load working in the members. This graph is utilized to detect buckling in dome structures. Similarly, in Figure 25 (b), P - δ_{mid} represents the axial compression load P graph and the relative flexural translation position at the member's middle (δ_{mid}). Here, δ_{mid} represents the flexural translation from the link line middle between two member nodes to the member's middle after the translation position, and it changes with the member axial compression load. The P - δ_{mid} graph is also employed to detect buckling in dome structures.

**Figure 25.** Buckling mechanism in dome structures: P - δ relationship

The graph in Figure 26 shows a typical P - δ_{end} & P - δ_{mid} member graph obtained through geometric and material

nonlinearity in structural analysis (GMNA) of the dome structure. Member buckling transpires when the longitudinal compressive force decreases after reaching the final longitudinal compressive load. This results in a rise in the relative translation position between the two member extremities δ_{end} or a rise in the relative flexural translation position at the member middle δ_{mid} in the $P-\delta_{end}$ or $P-\delta_{mid}$ member graph. There are three types of buckling or member instability that may occur:

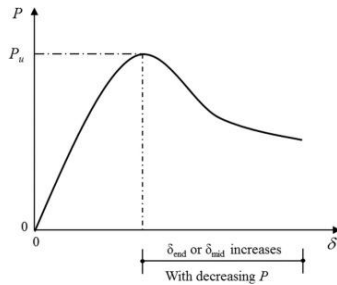


Figure 26. Standard approach for evaluating member buckling using $P-\delta_{end}$ and $P-\delta_{mid}$

1. Abrupt step-up of δ_{end} while δ_{mid} decreases, as displayed in Figure 27. This member instability type transpires when the limit rigidity of one member extremity is stronger than the other. This results in an ongoing upward trend in translation position δ_{end} after member buckling, resulting in the inclination of dome structure local region stiffness weakness members towards buckling.

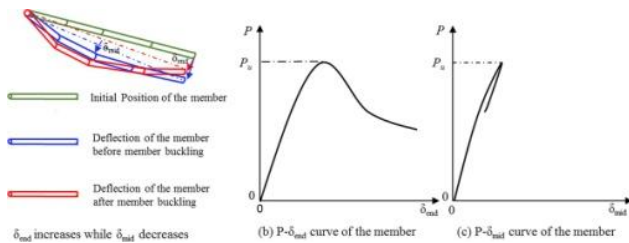


Figure 27. Investigating the first type of buckling in dome structure members

2. Abrupt step-up of δ_{mid} while δ_{end} decreases, as displayed in Figure 28. This member instability type transpires when there is nearness between one member extremity limit inflexibility to the other. This causes an ongoing upward trend in translation position δ_{mid} after member buckling, indicating dome structure member flexural rigidity failing leads this member to buckling tendency.

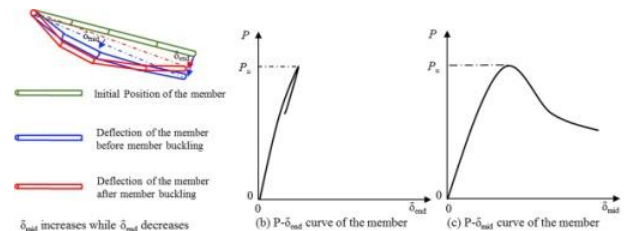


Figure 28. Investigating the second type of buckling in dome structure members

3. Abrupt step-up of both δ_{end} and δ_{mid} , as displayed in Figure 29. This buckling transpires when member longitudinal compressive load lessens after final longitudinal compressive load is achieved. The dome member flexural rigidity and limit inflexibility failing leads to member inclination towards this buckling. Member flexural rigidity and limit inflexibility hold inverse results. This results in complex and diverse member buckling in the dome.

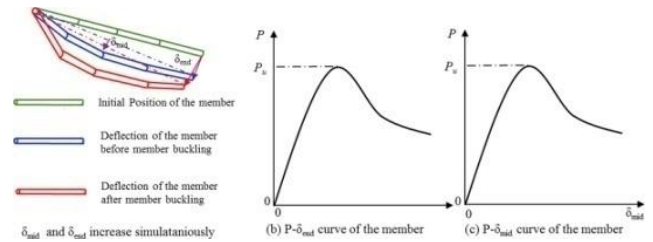


Figure 29. Investigating the third type of buckling in dome structure members

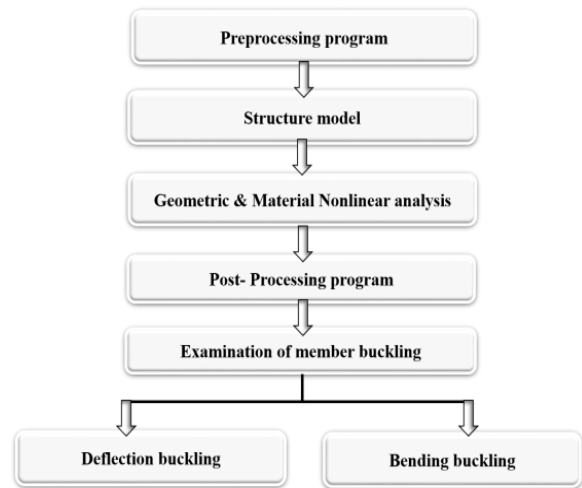


Figure 30. Detailed Flowchart to member buckling assessment

The complete work from connection rigidity definition, connection rigidity insertion into structure, to buckling given by run plan in detail in Figure 30.

4.2.1. Instability Generation Analysis

To gain a more comprehensive understanding of aluminum dome instability, three sets of studies were selected and are listed in Table 6. To begin understanding the correlation between member buckling and complete dome buckling, the member buckling assessment was performed. The dome instability generation is divided into two families: bit-by-bit instability and simultaneous instability. In the bit-by-bit instability, member buckling occurs first, followed by a progressive increase in buckling members until the ultimate structural capacity of the structure is achieved. On the other hand, in simultaneous instability, a large number of members buckle, and the structure experiences complete buckling all at once. For the selected sets, the aluminum dome study followed the simultaneous instability form shown in the subsequent sections through member buckling assessment.

4.2.2. Set 1: Kiewitt6 Domes 40m

The load-position graph shown in Figure 31 (a) & (b) was generated by utilizing the GMNA method to examine the structure's response to loading. The corresponding buckling behavior is illustrated in Figure 32. Figure 31 displays three different phases labeled as α , β and ω for the f/l ratio of 1/5, and two phases labeled as α and ω for the f/l ratio of 1/8. The phase α marks the point where the dome attains 50% of its bearing capacity. The phase β indicates the instant when the dome reaches the nonlinear zone on the load-position graph just before achieving the ultimate structural capacity. This stage is also the onset of member buckling. The phase ω corresponds to the point where the dome attains its final bearing capacity. The phase β lies between α and ω . However it does not appear on the structure's load-position graph.

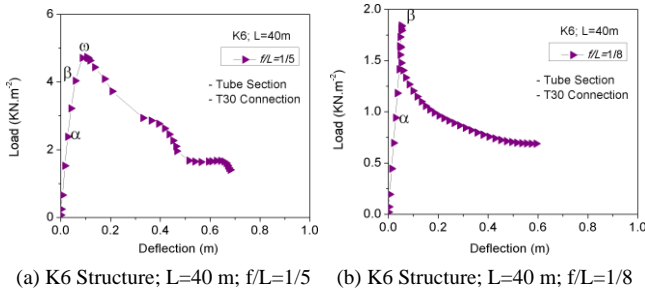


Figure 31. Load-deflection graphs for K6 structure with different L and f/L values

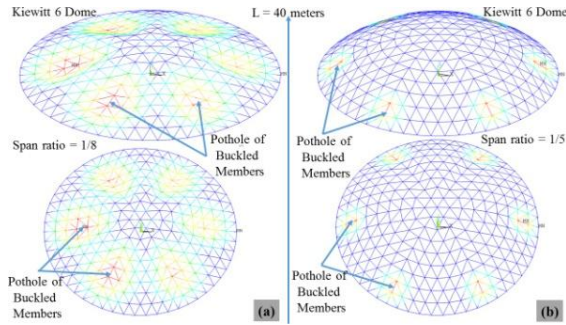


Figure 32. Analysis of deformation behavior in K6 dome structure under loading; L = 40 m

During the α phase, the Aluminum K6 dome with $f/l = 1/5$ reaches 50.21% of its bearing capacity. At this point, more than 21.16% of the members (160 members) tend to buckle simultaneously, although they are not buckled but rather bent halfway to the critical position, as displayed in Figure 33 (a). Nodes located on the ring members exhibit the greatest vertical displacement.

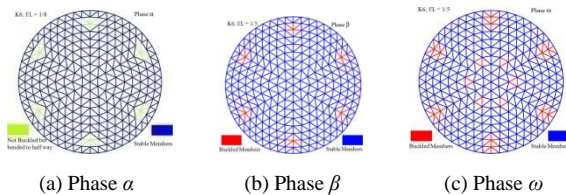


Figure 33. Assessment of K6 dome member buckling in phases α , β , and ω ($f/l = 1/5$)

At position β , the Aluminum K6 dome $f/l = 1/5$ gains 85.09% of its bearing capacity, and the structure starts the process of developing potholes.

Nodes located on the radial members exhibit the greatest vertical displacement. A complete of 36 members (4.76% of components) of the Aluminum K6 dome have buckled, including 12 radial members, 12 diagonal members, and 12 ring members, as displayed in Figure 33 (b).

At position ω , the Aluminum K6 dome $f/l = 1/5$ reaches its final bearing capacity, and crumpled members potholes appear. A total of 84 members (11.11% of the members) have buckled, traced by a considerable number of bent members at the same time, resulting in the complete buckling of the structure. The maximum vertical position of nodes remains on radial members, as displayed in Figure 33 (c). As displayed in Figure 32, the Aluminum K6 dome $f/l = 1/5$ shows buckled member potholes in every panel. This includes members between the secondary and tertiary circle and from the 7th ring to members between the 8th and 9th ring. As the load increases, the charge-position graph falls suddenly at position ω , as displayed in Figure 31(a).

To estimate buckled members, three illustrative members are chosen, and their $P-\delta_{end}$ graph and $P-\delta_{mid}$ graphs are used to appraise crumpled members (Figure 34). In each member's $P-\delta_{end}$ graph, the upright load axis is standardized against the member axial load at position ω (Figure 34 (a)). The horizontal position axis is standardized with member δ_{end} maximum appraisal. The vertical load axis is standardized with member axial load at the ω position in each member $P-\delta_{mid}$ graph. The horizontal position axis is standardized versus member δ_{mid} maximum estimation (Figure 34 (b)). The dome load-position graph in Figure 31 (a) is also standardized and plotted in Figure 34 (a) & (b). The load vertical axis is standardized versus member axial load at position ω , and the position horizontal axis is standardized with position maximum estimate.

Based on Figure 34 (a) & (b), the δ_{end} & δ_{mid} appraisals continue to increase after the final axial compression load is attained, despite a decrease in the members' axial compression load. These illustrative members exhibit the third buckling type, as described in section 4.2. The Mises equivalent stress ratio for each member's yield strength was calculated at the ω position, and the results were plotted as a member position function. All members, except for Member 3, the ring member, had the same ratio, indicating equal distribution of internal forces (Figure 35(a)). Similarly, the bending stress ratio to member axial stress at the ω position was plotted as a member position function, with all members having small ratio values (Figure 35(b)). Members had the same bending stress ratio to axial stress ratio, with the exception of Member 3, which had a larger deviation (Figure 35(a)). This suggests that member buckling will transpire at the dome's primary internal force transmission path. As a result, member buckling and complete buckling of the structure will occur simultaneously due to the simultaneous instability model.

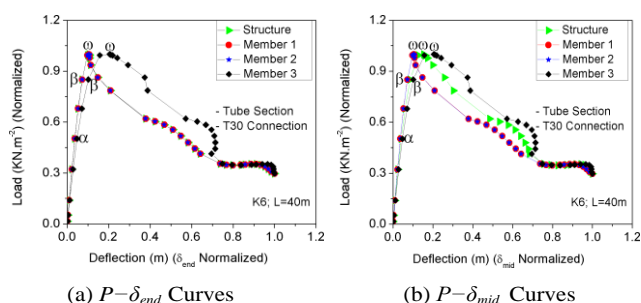


Figure 34. Assessment of Load-Deflection Relationships for K6 Structure

The findings from analyzing other domes are presented in Table 8, and the process followed for this analysis was similar to that for set 1-A and set 1-B. The analysis follows the Keys study features as explained earlier. The study

Table 8. Comparison of Three Sets of Aluminum Dome Study Results

Designation	Set 1			Set 2			Set 3		
Structure Type	K6			K8			K6		
Span	40m			40m			60m		
Phases	α	β	ω	α	β	ω	α	β	ω
Bearing Capacity (%)	50	—	100	50	—	100	50	—	100
Calculated Bearing Capacity (%)	50.21	85.09	100	56.55	79.98	100	55.56	85.94	100
Total Members	756	756	756	1008	1008	1008	1332	1332	1332
Bent Members	160	—	—	304	—	—	468	—	—
Bent Members (%)	21.16	—	—	30.16	—	—	35.14	—	—
Buckled members Potholes	×	✓	✓	×	✓	✓	×	✓	✓
Buckled Members	—	36	84	—	48	264	—	36	366
Buckled Members (%)	—	4.76	11.11	—	4.76	26.19	—	2.70	27.48
Max Vertical Position	○	↑	↑	↑	↑	↑	↗↘	↑	↑
Member axial compression load		↓			↓			↓	
St δ_{msd} & δ_{end}		↑			↑			↑	
Internal Forces		↔			↔			↔	
Members Von Miss Stress ratio		≈			≈			≈	
Structure Von Miss Stress ratio		≈			≈			≈	
Members bending Stress ratio		≪			≪			≪	
Structure bending Stress ratio		≪			≪			≪	
Buckling type		3 rd			3 rd			3 rd	
Buckled Members Paths		→			→			→	
Instability Mode									

Table 9. Comparative study of aluminum domes with $f/L = 1/8$ under different sets

Designation	Set 1			Set 2			Set 3		
Structure Type	K6			K8			K6		
Span	40m			40m			60m		
Phases	α	β	ω	α	β	ω	α	β	ω
Bearing Capacity (%)	50	--	100	50	--	100	50	--	100
Calculated Bearing Capacity (%)	50.21	--	100	54.49	87.34	100	80.52	--	100
Total Members	756	756	756	1008	1008	1008	1332	1332	1332
Bent Members	48	--	--	152	--	--	--	--	--
Bent Members (%)	6.35	--	--	15.08	--	--	--	--	--
Buckled members Potholes	✓	--	✓	✓	✓	✓	✓	-	✓
Buckled Members	--	--	90	--	240	304	--	36	180
Buckled Members (%)	--	--	11.90	--	23.81	30.16	--	2.70	13.51
Max Vertical Position	↑	-	↑	↑	↑	↑	↑	-	↑
Member axial compression load		↓			↓			↓	
St δ_{mid} & δ_{end}		↑			↑			↑	
Internal Forces		↔			↔			↔	
Members Von Miss Stress ratio		≈			≈			≈	
Structure Von Miss Stress ratio		≈			≈			≈	
Members bending Stress ratio		≪			≪			≪	
Structure bending Stress ratio		≪			≪			≪	
Buckling type		3 rd			3 rd			3 rd	
Buckled Members Paths		→			→			→	
Instability Mode									

4.3. Aluminum and Steel Dome Comparison Study

The present study involves a comparison of Aluminum and Steel domes previously examined in [22]. The outcomes of the investigation are summarized in Table 10 & Table 11. The comparison study of Aluminum and Steel domes revealed that both materials exhibit similar key parameters that impact dome instability, albeit with slight variations. Additionally, both materials display the same instability pattern with only minor percentage differences.

In conclusion, the study of monolithic semi-rigidly partially flexible jointed dome structural integrity is significant. This study offers valuable understanding into their design and engineering. Through the analysis of various parametric quantities affecting dome instability, it has been established that connection bending stiffness, geometric imperfections, load distribution ratio, ring frequency, span and rise/span ratio, members' cross-section, and plasticity development are critical factors. On the Basis of the

investigations, the following essential findings were made:

1. Key parametric quantities affecting dome instability include connection bending stiffness, early geometric imperfection, load distribution ratio, ring frequency, span and rise/span ratio, members cross-section, and plasticity development.
2. Members and connections in the plasticity development area are more prone to instability as dome instability grows from summit close members to peripheral members.
3. The analysis identified the key features affecting Aluminum dome instability capacity, laying further milestones in single-layer semi-rigidly jointed Aluminum dome foundation for engineering applications.
4. The $P-\delta$ and $P-\delta$ member graphs, paired with buckling definition precondition, are efficient in identifying buckled members in dome structure instability analysis procedures.

Table 10. Analyzing the structural integrity of Aluminum and Steel Domes

Designation Structure type	Aluminum material		Steel material	
	K8		K8	
f/L	1/8	1/5	1/8	1/5
Joint bending stiffness effect on critical load	↑	↑	↑	↑
Early geometric imperfection effect on critical load	↓	↓	↓	↓
Load distribution effect on critical load	↓	↓	↓	↓
Ring frequency effect on critical load	↑	↑	↑	↑
Rise/span ratio effect on critical load	↑	↑	↑	↑
Instability opening (from summit)	∈ 4 th & 5 th ○	∈ 2 nd & 3 rd ○	2 nd ○	2 nd ○
Instability development zone magnitude	∈ 8 th & 9 th ○	∈ 8 th & 9 th ○	2 nd ○	2 nd ○
Plasticity development opening	∈ 4 th & 5 th ○	∈ 2 nd & 3 rd ○	2 nd ○	2 nd ○
Plasticity development zone magnitude	∈ 8 th & 9 th ○	∈ 8 th & 9 th ○	2 nd ○	2 nd ○
Plasticity increment magnitude	Eight	Eight	Nine	Nine
Stable members (%)	35	40	10	10
Unstable members (%)	65	60	90	90
Buckled members (%)	9	9	60	60
Bent members (%)	56	52	30	30
Buckled Members Paths	→	→	→	→

Table 11. Analysis of Aluminum and Steel Domes [22]: A Comprehensive Comparison

Designation	Aluminum material				Steel material	
	K8				K8	
Structure Type	α	β	ω	a	b	c
Phases						
Bearing Capacity (%)	50	—	100	50	—	100
Calculated Bearing Capacity (%)	50 – 80	70 – 86	100	96	—	100
Bent Members (%)	5 – 40	—	—	3.2	5	30
Buckled members Potholes	×	✓	✓	×	×	×
Buckled Members (%)	—	2 – 25	10 – 35	5	30	60
Max Vertical Position	↑	↑	↑	○	○	○
Member axial compression load		↓			↓	
St δ_{mid} & δ_{end}		↓			↓	
Internal Forces		↔			↔	
Members Von Miss Stress ratio		≈			≈	
Structure Von Miss Stress ratio		≈			≈	
Members bending Stress ratio		≪			≪	
Structure bending Stress ratio		≪			≪	
Buckling type		3 rd			3 rd	
Buckled Members Paths		→			→	
Instability Mode						

5. The analysis found that all sets studied hold the third buckling type, and members present equal von Mises stress ratio versus yield strength and equal bending stress ratio versus axial stress with the overall structure. Member buckling happens at the structure's principal internal force transmission path, and member buckling and structure complete buckling occur simultaneously.
6. The instability pattern is simultaneous instability, where one bent or buckled member can cause a domino effect, leading to structure complete buckling.
7. The comparison of Aluminum and Steel domes findings shows that they have the same instability pattern, with slight variances. However, Aluminum dome structures have a higher load-carrying capacity when the connection bending stiffness, ring frequency, and span and rise/span ratio are increased. This study lays further milestones in the engineering application of monolithic semi-rigidly jointed Aluminum dome structures.
8. The study's findings are essential in improving the design and construction of semi-rigidly jointed single-layer dome structures, particularly Aluminum domes.

Overall, the results of this study offers useful information for the design process and engineering of dome structures and ensure their stability and safety. Further research in this area could explore the use of other materials and innovative designs to optimize dome structures' load-carrying capacity and stability.

Data Availability Statement

Some or all data, models, or code that support the findings of this study are available from the corresponding author upon reasonable request.

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Conict of Interest Statement

On behalf of all authors, the corresponding author states that there is no conict of interest.

Notation

$M-\theta$ = moment-rotation behavior of the connection;
 n = Ring frequency of reticulated dome;
 f = Rise of dome;

L = Span of reticulated dome;
 P = Axial force of the member;
 n = Parameter defined by Ramberg-Osgood expression is used to describe the shape of the inelastic portion of the stress-strain diagram
 E_0 = Initial Elastic Modulus;
 δ_{mid} = Relative bending deflection of the mid- point of the member;
 δ_{end} = Relative deflection between the two ends of the member;
 $\sigma_{0.1}$ = Nominal yield strength (stress at 0.1 percent plastic strain) or 0.1% proof stress;
 $\sigma_{0.2}$ = Nominal yield strength (stress at 0.2 percent plastic strain) or 0.2% proof stress;
 σ_u = Ultimate strength;
GNA = Geometric nonlinear analysis;
GMNA = Geometric and material nonlinear analysis;
 d = Deflection vector of the dome;
 R = Radius of curvature;
 θ_0 = Half-subtended angle: inclination of the roof for the members at the dome apex;
 τ = Ultimate Shear Stress;
 σ = Compressive Stress or Ultimate Tensile Stress;
FEM = Finite element model;
 σ_{uFE} = Ultimate stress from FEM;
 E_0 = Youngs modulus;
 K_i = Connection Initial Stiffness;
 K_u = Connection Plastic Stiffness;
 M_p = Connection Plastic Moment;
 M_u = Connection Ultimate Moment;
T18-1, T24-1 & T30-1 Specimen nominal name in bolts direction;
T18-2, T24-2 & T30-2 Specimen nominal name perpendicular to bolts direction;
 L = domes span;

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